

Inference in non parametric Hidden Markov Models

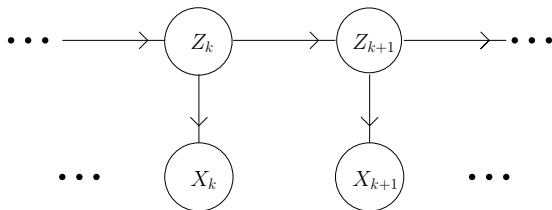
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Hidden Markov models (HMMs)



Observations $(X_k)_{k \geq 1}$ are independent conditionally to $(Z_k)_{k \geq 1}$

$$\mathcal{L}((X_k)_{k \geq 1} | (Z_k)_{k \geq 1}) = \bigotimes_{k \geq 1} \mathcal{L}(X_k | Z_k)$$

Latent (unobserved) variables $(Z_k)_{k \geq 1}$ form a Markov chain

Finite state space stationary HMMs

The Markov chain is stationary, has **finite state space** $\{1, \dots, K\}$ and **transition matrix** Q . The stationary distribution is denoted μ .

Conditionnally to $Z_k = j$, X_k has **emission distribution** F_j .

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Conditionnally to $Z_k = j$, X_k has **emission distribution** F_j .

The marginal distribution of any X_k is

$$\sum_{j=1}^K \mu(j) F_j$$

A finite state space HMM is a finite mixture with Markov regime

The use of hidden Markov models

Modeling **dependent** data arising from **heterogeneous populations**.

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Modeling **dependent** data arising from **heterogeneous populations**.

Markov regime : leads to **efficient algorithms** to compute :

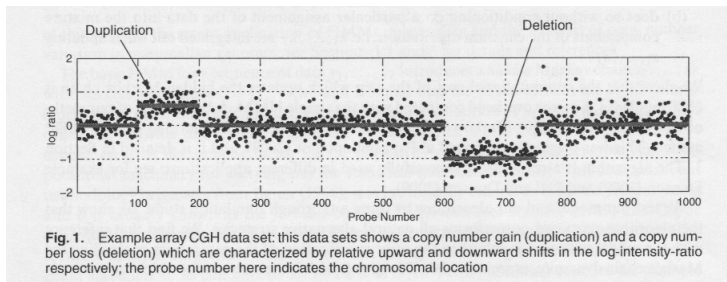
- Filtering/prediction/smoothing/ probabilities
(Forward/Backward recursions) : given a set of observations, the probability of hidden states.
- Maximum a posteriori (prediction of hidden states); Viterbi's algorithm.
- Likelihoods and EM algorithms : estimation of the transition matrix Q and the emission distributions F_1, \dots, F_K
- MCMC Bayesian methods

The parametric/non parametric story

The inference theory is well developed in the parametric situation where for all j , $F_j \in \{F_\theta, \theta \in \Theta\}$ with $\Theta \subset \mathbb{R}^d$.

But parametric modeling of emission distributions may lead to poor results in particular applications.

Motivating example : DNA copy number variation using DNA hybridization intensity along the genome



Popular approach : HMM with emission distributions $\mathcal{N}(m_j; \sigma^2)$ for state j .

Sensitivity to outliers, skewness or heavy tails that may lead to large numbers of false copy number variants detected.

→ **Non parametric Bayesian algorithms** : Yau, Papaspiliopoulos, Roberts, Holmes (JRSSB 2011)

Other examples in which **the use of nonparametric algorithms improves performances**

- Bayesian methods
 - ▶ Climate state identification (Lambert et al. 2003)
- EM-style algorithms
 - ▶ Voice activity detection (Couvreur et al., 2000)
 - ▶ Facial expression recognition (Shang et al. 2009)

Finite state space non parametric HMMs

The marginal distribution of any X_k is $\sum_{j=1}^K \mu(j) F_j$

Non parametric mixtures are not identifiable with no further assumptions

$$\begin{aligned} & \mu(1) F_1 + \mu(2) F_2 + \dots + \mu(K) F_K \\ &= (\mu(1) + \mu(2)) \left[\frac{\mu(1)}{\mu(1) + \mu(2)} F_1 + \frac{\mu(2)}{\mu(1) + \mu(2)} F_2 \right] + \dots + \mu(K) F_K \\ &= \frac{\mu(1)}{2} F_1 + \frac{\left[\frac{\mu(1)}{2} F_1 + \mu(2) F_2 \right]}{\frac{\mu(1)}{2} + \mu(2)} + \dots + \mu(K) F_K \end{aligned}$$

Why do non parametric HMM algorithms work???

Dependence of observed variables has to help!

Basic questions

Denote $\mathbb{F} = (F_1, \dots, F_K)$.

For m an integer, let $\mathbb{P}_{K;Q;\mathbb{F}}^{(m)}$ be the distribution of (X_1, \dots, X_m) .

The sequence of observed variables has mixing properties : adaptive estimation of $\mathbb{P}_{K;Q;\mathbb{F}}^{(m)}$ is possible. Can one get information on K , Q and \mathbb{F} from an estimator $\widehat{\mathbb{P}}^{(m)}$ of $\mathbb{P}_{K;Q;\mathbb{F}}^{(m)}$?

- **Identifiability** : for some m ,

$$\mathbb{P}_{K_1;Q_1;\mathbb{F}_1}^{(m)} = \mathbb{P}_{K_2;Q_2;\mathbb{F}_2}^{(m)} \implies K_1 = K_2, Q_1 = Q_2, \mathbb{F}_1 = \mathbb{F}_2.$$

- **Inverse problem** : Build estimators \widehat{K} , \widehat{Q} and $\widehat{\mathbb{F}}$ such that one may deduce consistency/rates from those of $\widehat{\mathbb{P}}^{(m)}$ as an estimator of $\mathbb{P}_{K;Q;\mathbb{F}}^{(m)}$.

Joint work with [Judith Rousseau](#) (*translated emission distributions; Bernoulli 2016*)

Joint work with [Alice Cleynen](#) and [Stéphane Robin](#) (*General identifiability; Stat. and Comp. 2016*),
[Yohann De Castro](#) and [Claire Lacour](#) (*Adaptive estimation via model selection and least squares; JMLR 2016*),
[Yohann De Castro](#) and [Sylvain Le Corff](#) (*Spectral estimation and estimation of filtering/smoothing probabilities; IEEE IT to appear*),

Work by [Elodie Vernet](#) (*Bayesian estimation; consistency EJS 2015 and rates Bernoulli in revision*)

Work by [Luc Lehéricy](#) (*Estimation of K ; submitted; state by state adaptivity; submitted*)

Work by [Augustin Tournon](#) (*Climate applications; PHD in progress*)

Identifiability/inference theoretical results in nonparametric HMMs

- 1 Identifiability in non parametric finite translation HMMs and extensions
- 2 Identifiability in non parametric general HMMs
- 3 Generic methods
- 4 Inverse problem inequalities
- 5 Further works

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Translated emission distributions

Here we assume that there exists a distribution function F and real numbers m_1, \dots, m_K such that

$$F_j(\cdot) = F(\cdot - m_j), \quad j = 1, \dots, K.$$

The observations follow

$$X_t = m_{Z_t} + \epsilon_t, \quad t \geq 1,$$

where the variables ϵ_t , $t \geq 1$, are i.i.d. with distribution function F , and are independent of the Markov chain $(Z_t)_{t \geq 1}$.

Previous work : independent variables ; $K \leq 3$; symmetry assumption on F : Bordes, Mottelet, Vandekerkhove (Annals of Stat. 2006) ; Hunter, Wang, Hettmansperger (Annals of Stat. 2007) ; Butucea, Vandekerkhove (Scandinavian J. of Stat, to appear).

Identifiability : assumptions

For $K \geq 2$, let Θ_k be the set of $\theta = (m, (Q_{i,j})_{1 \leq i,j \leq K, (i,j) \neq (K,K)})$ satisfying :

- Q is a probability mass function on $\{1, \dots, K\}^2$ such that $\det(Q) \neq 0$,
- $m \in \mathbb{R}^K$ is such that $m_1 = 0 < m_2 < \dots < m_k$.

For **any distribution function** F on \mathbb{R} , denote $\mathbb{P}_{(\theta, F)}^{(2)}$ the law of (X_1, X_2) :

$$\mathbb{P}_{(\theta, F)}^{(2)}(A \times B) = \sum_{i,j=1}^K Q_{i,j} F(A - m_i) F(B - m_j).$$

Identifiability result

Theorem [EG, J. Rousseau (Bernoulli 2016)]

Let F and \tilde{F} be distribution function on \mathbb{R} , $\theta \in \Theta_K$ and $\tilde{\theta}$ in $\Theta_{\tilde{K}}$.
Then

$$\mathbb{P}_{\theta, F}^{(2)} = \mathbb{P}_{\tilde{\theta}, \tilde{F}}^{(2)} \implies K = \tilde{K}, \theta = \tilde{\theta} \text{ and } F = \tilde{F}.$$

- **No assumption on F !**
- HMM not needed ; **dependent (stationary) state variables** suffice.
- Extension (by projections) to **multidimensional** variables.
- Identification of **ℓ -marginal distribution**, i.e. the law of (Z_1, \dots, Z_ℓ) , K and F using the law of (X_1, \dots, X_ℓ) .

Identifiability : sketch of proof

ϕ_F : characteristic function of F ; $\phi_{\tilde{F}}$: c.f. of \tilde{F} ;

$\phi_{\theta,i}$: $(\phi_{\tilde{\theta},i})$ c.f. of the law of m_{Z_i} under $P_{\theta,F}$, (under $P_{\tilde{\theta},\tilde{F}}$);

Φ_θ : $(\Phi_{\tilde{\theta}})$ c.f. of the law of (m_{Z_1}, m_{Z_2}) under $P_{\theta,F}$ (under $P_{\tilde{\theta},\tilde{F}}$).

The c.f. of the law of X_1 , of X_2 , then of (X_1, X_2) , give

$$\phi_F(t) \phi_{\theta,1}(t) = \phi_{\tilde{F}}(t) \phi_{\tilde{\theta},1}(t),$$

$$\phi_F(t) \phi_{\theta,2}(t) = \phi_{\tilde{F}}(t) \phi_{\tilde{\theta},2}(t),$$

$$\phi_F(t_1) \phi_F(t_2) \Phi_\theta(t_1, t_2) = \phi_{\tilde{F}}(t_1) \phi_{\tilde{F}}(t_2) \Phi_{\tilde{\theta}}(t_1, t_2).$$

We thus get for all $(t_1, t_2) \in \mathbb{R}^2$,

$$\begin{aligned} \phi_F(t_1) \phi_F(t_2) \Phi_\theta(t_1, t_2) \phi_{\tilde{\theta},1}(t_1) \phi_{\tilde{\theta},2}(t_2) \\ = \phi_F(t_1) \phi_F(t_2) \Phi_{\tilde{\theta}}(t_1, t_2) \phi_{\theta,1}(t_1) \phi_{\theta,2}(t_2). \end{aligned}$$

Identifiability : sketch of proof

Thus on a neighborhood of 0 in which ϕ_F is non zero :

$$\Phi_{\theta}(t_1, t_2) \phi_{\tilde{\theta},1}(t_1) \phi_{\tilde{\theta},2}(t_2) = \Phi_{\tilde{\theta}}(t_1, t_2) \phi_{\theta,1}(t_1) \phi_{\theta,2}(t_2).$$

Then

- Equation extended to the complex plane (**entire functions**).
- The set of zeros of $\phi_{\theta,1}$ coincides with the set of zeros of $\phi_{\tilde{\theta},1}$ (here $\det(Q) \neq 0$ is used).
- **Hadamard's factorization theorem** allows to prove that
$$\phi_{\theta,1} = \phi_{\tilde{\theta},1}.$$
- Same proof for $\phi_{\theta,2} = \phi_{\tilde{\theta},2}$, leading to $\Phi_{\theta} = \Phi_{\tilde{\theta}}$, and then
$$\phi_F = \phi_{\tilde{F}}$$

Finally **the characteristic function characterizes the law**, so that $K = \tilde{K}$, $\theta = \tilde{\theta}$ and $F = \tilde{F}$.

Identifiability : estimation of θ

$$\Phi_{\theta}(t_1, t_2) \phi_{X_1}(t_1) \phi_{X_2}(t_2) - \Phi_{(X_1, X_2)}(t_1, t_2) \phi_{\theta, 1}(t_1) \phi_{\theta, 2}(t_2) = 0.$$

- Replace $\phi_{X_1}(t_1)$, $\phi_{X_2}(t_2)$ and $\Phi_{(X_1, X_2)}(t_1, t_2)$ by estimators (ex : empirical estimators) to get an empirical contrast (take the square of the modulus and integrate).
- Preliminary estimator : penalize to get consistent estimators of K and θ satisfying the assumptions.
- $\hat{\theta}_n$ minimize the contrast over a suitable compact.

$\hat{\theta}_n$ is \sqrt{n} -consistent + asymptotic distr. + deviation inequalities [G. Rousseau (Bernoulli 2016)]

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Finite state space HMM : Connexion with mixtures of independent variables

The distribution of (X_1, X_2, X_3) may be written as

$$\begin{aligned}\mathbb{P}_{Q, \mathbb{F}}^{(3)} &= \sum_{i=1}^K \sum_{j=1}^K \sum_{m=1}^K \mu(i) Q_{i,j} Q_{j,m} F_i \otimes F_j \otimes F_m \\ &= \sum_{j=1}^K \mu(j) \left(\sum_{i=1}^K \frac{\mu(i) Q_{i,j}}{\mu(j)} F_i \right) \otimes F_j \otimes \left(\sum_{m=1}^K Q_{j,m} F_m \right) \\ &= \sum_{j=1}^K \mu(j) G_{j,1} \otimes G_{j,2} \otimes G_{j,3}\end{aligned}$$

which is a **mixture of K populations**, in each population the observation is that of **independent** variables.

Z_1 and Z_3 are independent conditionally to Z_2 .

→ Use results about mixtures of independent variables.

An old result by Kruskal

Kruskal's algebraic result (1977) : 3-way contingency tables are identifiable (up to label switching) under some Kruskal's rank assumption.

Kruskal + adequate approximation argument : Non parametric mixtures in which, conditionally to the population, at least 3 variables are independent, are identifiable under some linear independence assumption of the conditional probability distributions of those variables. (Allman et al. , 2009)

Theorem (A. Cleyne, S. Robin, EG, 2016 Stat. and Comput.)

Assume that the probability measures F_1, \dots, F_K are linearly independent and that Q has full rank. Then the parameters K, Q and F_1, \dots, F_K are identifiable from the distribution of 3 consecutive observations X_1, X_2, X_3 , up to label swapping of the hidden states.

Mixtures of independent variables : spectral analysis

Works by Anandkumar, Dai, Hsu, Kakade, Song, Zhang, Xie.

Let $X = (X_1; X_2; X_3)$ have distribution $\otimes_{d=1}^3 G_{j,d}$ conditionally to $Z = j$ so that X has distribution

$$\sum_{j=1}^K \mu(j) \otimes_{d=1}^3 G_{j,d}$$

Let $\varphi_1, \dots, \varphi_M$ be M real valued functions.
For $d = 1, 2, 3$, define $A^{(d)}$ the $M \times K$ matrix such that

$$A_{l,j}^{(d)} = \int \varphi_l dG_{j,d} = E[\varphi_l(X_d) | Z = j]$$

$$A^{(d)} = \begin{pmatrix} \int \varphi_1 dG_{1,d} & \cdots & \int \varphi_1 dG_{K,d} \\ \vdots & \vdots & \vdots \\ \int \varphi_M dG_{1,d} & \cdots & \int \varphi_M dG_{K,d} \end{pmatrix}$$

Mixtures of independent variables : spectral analysis

Let $D = \text{Diag}(\mu(1), \dots, \mu(K))$.

Let S the $M \times M$ matrix such that $S_{l,m} = E[\varphi_l(X_1)\varphi_m(X_2)]$.

Then,

$$S = A^{(1)}D(A^{(2)})^T.$$

If for all $d = 1, 2, 3, \dots, K$, $G_{1,d}, \dots, G_{K,d}$ are linearly independent, then for large enough M , $\text{rank}(A^{(d)}) = K$ and

$$\text{rank}(S) = K.$$

Let U_1 and U_2 be $M \times K$ matrices such that $U_1^T S U_2$ is invertible (may be found by SVD of S).

$$U_1^T S U_2 = \left(U_1^T A^{(1)} \right) D \left((A^{(2)})^T U_2 \right).$$

Mixtures of independent variables : spectral analysis

Define T be the $M \times M \times M$ tensor such that

$$T(l_1, l_2, l_3) = E[\varphi_{l_1}(X_1)\varphi_{l_2}(X_2)\phi_{l_3}(X_3)].$$

Let $V \in \mathbb{R}^M$, and define $T[V]$ the $M \times M$ matrix such that

$$T[V]_{l,m} = E[\varphi_l(X_1)\varphi_m(X_2)\langle V, \Phi(X_3) \rangle]$$

where $\Phi(X_3) = (\varphi_h(X_3))_{1 \leq h \leq M}$. Then

$$T[V] = A^{(1)} D \cdot \text{Diag} \left((A^{(3)})^T V \right) (A^{(2)})^T$$

Define

$$B(V) = (U_1^T T[V] U_2) (U_1^T S U_2)^{-1}.$$

Then, one has

$$B(V) = (U_1^T A^{(1)}) \text{Diag} \left((A^{(3)})^T V \right) (U_1^T A^{(1)})^{-1}.$$

Mixtures of independent variables : spectral analysis

$$U_1^T S U_2 = \left(U_1^T A^{(1)} \right) D \left((A^{(2)})^T U_2 \right)$$

$$\left(U_1^T S U_2 \right)^{-1} = \left((A^{(2)})^T U_2 \right)^{-1} D^{-1} \left(U_1^T A^{(1)} \right)^{-1}$$

$$T[V] = A^{(1)} D \cdot \text{Diag} \left((A^{(3)})^T V \right) (A^{(2)})^T$$

$$\begin{aligned} B(V) &= (U_1^T T[V] U_2) (U_1^T S U_2)^{-1} \\ &= U_1^T A^{(1)} D \cdot \text{Diag} \left((A^{(3)})^T V \right) (A^{(2)})^T U_2 (U_1^T S U_2)^{-1} \\ &= U_1^T A^{(1)} \text{Diag} \left((A^{(3)})^T V \right) \cdot D (A^{(2)})^T U_2 (U_1^T S U_2)^{-1} \\ &= (U_1^T A^{(1)}) \text{Diag} \left((A^{(3)})^T V \right) (U_1^T A^{(1)})^{-1}. \end{aligned}$$

Mixtures of independent variables : spectral analysis

Recall

$$B(V) = (U_1^T T[V] U_2)(U_1^T S U_2)^{-1} = (U_1^T A^{(1)}) \text{Diag} \left((A^{(3)})^T V \right) (U_1^T A^{(1)})$$

All matrices $B(V)$ have the same eigenvectors, and eigenvalues the coordinates of $(A^{(3)})^T V$.

By exploring various vectors V , one may recover $A^{(3)}$. The eigenvectors stay the same when permuting coordinates 2 and 3 of the observed variable, so that one may recover $A^{(2)}$, and thus also $A^{(1)}$. Recovering D is then also possible. Then, by taking M to infinity, one may recover the whole distributions $G_{1,j}$, $G_{2,j}$ and $G_{3,j}$, $j = 1, \dots, K$.

One may recover $\mu(1), \dots, \mu(K)$ and $G_{1,j}$, $G_{2,j}$ and $G_{3,j}$, $j = 1, \dots, K$ using Singular Value/ Eigen Value decompositions of matrices built from the distribution of $X = (X_1, X_2, X_3)$.

Spectral analysis : estimation

Emission distributions with densities f_j^* , $j = 1, \dots, K$ in $\mathbf{L}^2(\mathcal{X})$.

- Use a sieve of finite dimensional subspaces with orthonormal basis $\Phi_M := \{\varphi_1, \dots, \varphi_M\}$.
Examples : histograms ; splines ; Fourier ; wavelets.
- Estimation of Q^* and $\langle f_j^*, \varphi_m \rangle$, $j = 1, \dots, K$, $m = 1, \dots, M$ on the basis of the empirical distribution of the three-dimensional marginal, i.e. the distribution of (X_1, X_2, X_3)
Uses only one SVD, matrix inversions and one diagonalization.

$$\|\hat{Q} - Q^*\|^2 \text{ and } \|\hat{f}_{M,j} - f_{M,j}^*\|^2 \text{ are } O_P\left(\frac{M^3}{n}\right)$$

(De Castro, G., Le Corff, IEEE IT to appear)

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Model selection via penalized contrast

Define a contrast function $\gamma_n(g)$, g a possible density such that $\gamma_n(g) - \gamma_n(g^*)$ has positive limit for $g \neq g^*$, g^* being the true density.

The possible densities g have a particular form depending on the emission densities and a parametric part : $g := g_{\theta, F}$.

A sieve for the emission distributions leads to sieves on the possible densities $\mathcal{S}(\theta, M)$.

For the parametric part, we have in hand an estimator $\hat{\theta}$ that converges at parametric (or nearly parametric) rate.

For each M , define \hat{g}_M as the minimizer of $\gamma_n(g)$ for $g \in \mathcal{S}(\hat{\theta}, M)$. Set a penalty function $pen(n, M)$ and choose

$$\hat{M} = \arg \min_{M=1, \dots, n} \{ \gamma_n(\hat{g}_M) + pen(n, M) \}.$$

Then the estimator of g^* is $\hat{g} = g_{\hat{\theta}, \hat{F}}$, and the estimator of F^* is \hat{F} such that

$$\hat{g} = g_{\hat{\theta}, \hat{F}}.$$

Model selection via penalized contrast

Translation mixtures with dependent regime

Recall that the observations follow :

$$X_t = m_{Z_t} + \epsilon_t, \quad t \geq 1,$$

where the variables ϵ_t , $t \geq 1$, are i.i.d. with distribution function F , and are independent of the Markov chain $(Z_t)_{t \geq 1}$.

When $\theta = ((m_j)_j, (Q_{i,j})_{i,j})$ is known, one may recover F from the marginal density $g_{\theta,F}$ of X_t .

If F has density f , then $g_{\theta,f} := g_{\theta,F}$ is given by :

$$g_{\theta,f}(x) = \sum_{j=1}^K \mu(j) f(x - m_j).$$

where $\mu(i) = \sum_{j=1}^K Q_{i,j}$. Given the estimator

$$\hat{\theta}_n = ((\hat{m}_i)_{1 \leq i \leq k^*}, (\hat{Q}_{i,j})_{(i,j) \neq (k^*, k^*)}), \text{ denote } \hat{\mu}(i) = \sum_{j=1}^{k^*} \hat{Q}_{i,j}.$$

Model selection via penalized contrast

Translation mixtures with dependent regime

Maximum marginal-likelihood :

$$\gamma_n(g) = -\frac{1}{n} \sum_{i=1}^n \log g(X_i).$$

The sieve $\mathcal{S}(\hat{\theta}, M)$ is the set of functions $g = \sum_{j=1}^K \hat{\mu}(j) f(x - \hat{m}_j)$ where $f \in \mathcal{F}_M$:

$$\mathcal{F}_M = \left\{ \sum_{i=1}^M \pi_i \varphi_{\beta_i}(x - \alpha_i), \alpha_i \in [-A_M, A_M], \beta_i \in [b_M, B], \right. \\ \left. \pi_i \geq 0, i = 1, \dots, p, \sum_{i=1}^p \pi_i = 1 \right\}$$

with φ_β the centered gaussian density with variance β^2 .

Model selection via penalized contrast

General finite state space HMMs

Here $\theta = Q$ the transition matrix of the hidden Markov chain. For $F = (f_1, \dots, f_K)$ emission densities, if π is the stationary distribution of Q , the density of (X_1, X_2, X_3) is given by

$$g_{\theta, F}(x_1, x_2, x_3) = \sum_{j_1, j_2, j_3=1}^K \pi(j_1) Q(j_1, j_2) Q(j_2, j_3) f_{j_1}(x_1) f_{j_2}(x_2) f_{j_3}(x_3).$$

Least squares :

$$\gamma_n(g) = \|g\|_2^2 - \frac{2}{n} \sum_{s=1}^{n-2} g(X_s, X_{s+1}, X_{s+2}).$$

As n tends to infinity, $\gamma_n(g) - \gamma_n(g^*)$ converges almost surely to $\|g - g^*\|_2^2$.

The sieve $\mathcal{S}(\hat{\theta}, M)$ is the set of functions $g_{\hat{\theta}, F}$ such that

$$\forall j = 1, \dots, K, \exists (a_{mj})_{1 \leq m \leq M} \in \mathbb{R}^M, f_j = \sum_{m=1}^M a_{mj} \varphi_m.$$

Oracle inequalities (in general)

There exist constants κ , C and n_0 such that : if

$$\text{pen}(n, M) \geq \kappa \text{ complexity}(M) \frac{\log n}{n},$$

then for all $x > 0$, for all $n \geq n_0$, with probability $1 - e^{-x}$, it holds

$$D^2(\hat{g}, g^*) \leq C \left\{ \inf_M [d^2(g_M^*, g^*) + \text{pen}(n, M)] + \text{small terms} \right\}.$$

- Proof : concentration inequality + control of the complexity of the Sieve (ex : using bracketing entropy).
- Adaptive rates ; automatic best compromise bias/variance.
- Penalty in practice : slope heuristics.

Oracle inequalities : Translation mixtures and HMMs

Additional difficulty : deal with $\hat{\theta}$ in γ_n .

C depends here on the hidden chain (concentration inequality for dependent variables).

Translation mixtures with dependent regime

Oracle inequality using penalized m.l.e (G. , Rousseau [Bernoulli 2016]).

$D^2(\hat{g}, g^*)$: Hellinger's distance.

$d^2(g_M^*, g^*)$: Kullback's divergence.

General finite state space HMMs

Oracle inequality using least squares (De Castro, G. Lacour [JMLR 2016]).

$D^2(\hat{g}, g^*)$ and $d^2(g_M^*, g^*)$: L_2 -square distance.

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General question

Consistent estimation of g^* translates to consistent estimation of F^* .

Do adaptive minimax rates for the estimation of g^* translate to adaptive minimax rates for the estimation of F^* ?

Inverse problem : translation mixtures

Recall $g^* = \sum_{j=1}^K \mu^*(j) f^*(x - m_j^*)$.

G., Rousseau, Bernoulli 2016

If f^* has bounded derivative,

$$\left(2 \max_j \hat{\mu}(j) - 1\right) \left\| \hat{f} - f^* \right\|_1 \leq 2h(g^*, \hat{g}) + (1 + \|(f^*)'\|_\infty) \|\hat{\theta}_n - \theta^*\|.$$

Consequence : if $\max_j \mu^*(j) > \frac{1}{2}$, results on $h^2(g^*, \hat{g})$ and $\|\hat{\theta}_n - \theta^*\|$ translate to results on $\left\| \hat{f} - f^* \right\|_1$.

Remark : $\phi_{g^*} = \phi_{f^*} \phi_{\theta^*}$ with $\phi_{\theta^*}(t) = \sum_{j=1}^K \mu^*(j) e^{im_j^* t}$, and $\phi_{\theta^*}(t) \neq 0$ for all t if and only if $\max_j \mu^*(j) > \frac{1}{2}$ (Moreno 1973).

Proof

Proof : starts from $\|g^* - \hat{g}\|_1^2 \leq 4h^2 (g^*, \hat{g})$. Then,

$$\begin{aligned}\|g^* - \hat{g}\|_1 &= \left\| \sum_{j=1}^K \mu^*(j) f^*(y - m_j^*) - \sum_{j=1}^K \hat{\mu}(j) \hat{f}(\cdot - \hat{m}_j) \right\|_1 \\ &\geq \left\| \sum_{j=1}^K \hat{\mu}(j) (\hat{f} - f^*)(\cdot - \hat{m}_j) \right\|_1 \\ &\quad - \left\| \sum_{j=1}^K \mu^*(j) f^*(y - m_j^*) - \sum_{j=1}^K \hat{\mu}(j) f^*(\cdot - \hat{m}_j) \right\|_1 \\ &\geq \left\| \sum_{j=1}^K \hat{\mu}(j) (\hat{f} - f^*)(\cdot - \hat{m}_j) \right\|_1 - (1 + \|(f^*)'\|_\infty) \|\hat{\theta}_n - \theta^*\|_1\end{aligned}$$

Then using the triangle inequality,

$$\left\| \sum_{j=1}^K \hat{\mu}(j) (\hat{f} - f^*)(\cdot - \hat{m}_j) \right\|_1 \geq \left(2 \max_j \hat{\mu}(j) - 1 \right) \left\| \hat{f} - f^* \right\|_1.$$

Inverse problem : non parametric HMMs

Recall that for $F = (f_1, \dots, f_K)$ emission densities and Q a transition matrix with stationary distribution π ,

$$g_{Q,F}(x_1, x_2, x_3) = \sum_{j_1, j_2, j_3=1}^K \pi(j_1) Q(j_1, j_2) Q(j_2, j_3) f_{j_1}(x_1) f_{j_2}(x_2) f_{j_3}(x_3).$$

Assumption : $P(Q^*, \langle f_j^*, f_j^* \rangle) \neq 0$ P polynomial

→ generically satisfied

→ always satisfied if $K = 2$

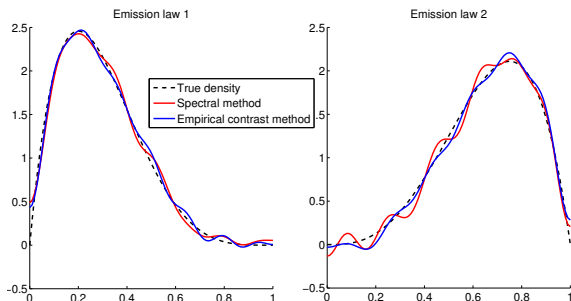
Theorem (Y. de Castro, EG, C. Lacour, JMLR 2016)

There exists $C > 0$ such that for all Q in a neighborhood of Q^* ,

$$\|g_{Q,F^*} - g_{Q,F}\|_2 \geq C \sum_{j=1}^K \|f_j^* - f_j\|_2.$$

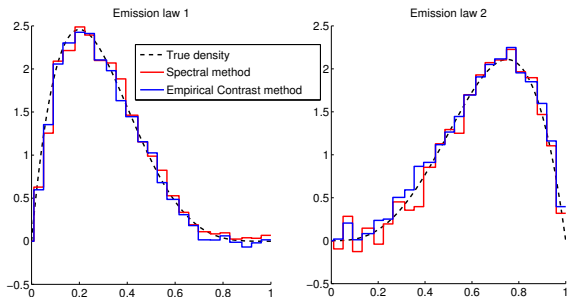
Thus, results on $\|g^* - \hat{g}\|_2$ translate to results on $\sum_{j=1}^K \|f_j^* - \hat{f}_j\|_2$.

Simulations : $K=2$



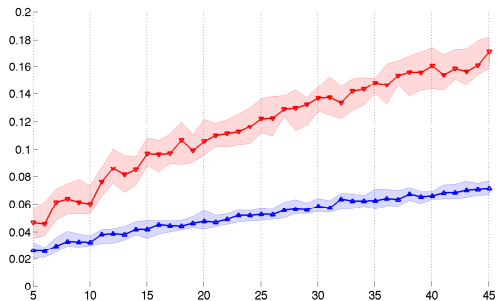
Reconstruction of densities f_1 and f_2 (Beta distributions) with
spectral and **least squares** methods
($N = 50000$, trigonometric basis)

Simulations : $K=2$



Reconstruction of densities f_1 and f_2 (Beta distributions) with **spectral** and **least squares** methods ($N = 50000$, histogram basis)

Simulations : $K=2$



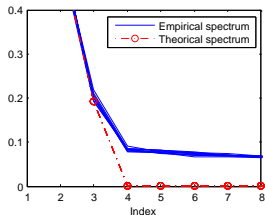
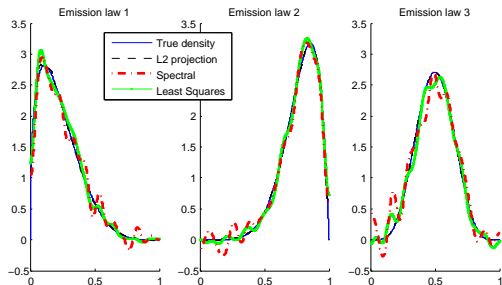
Integrated variance $\sum_{j=1}^2 E\|\hat{f}_j - f_{M,j}\|^2$ of **spectral** and **least squares** estimators, as a function of M ($N = 50000$, histogram basis)

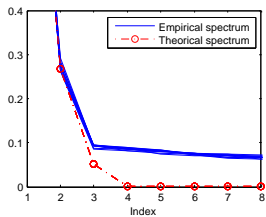
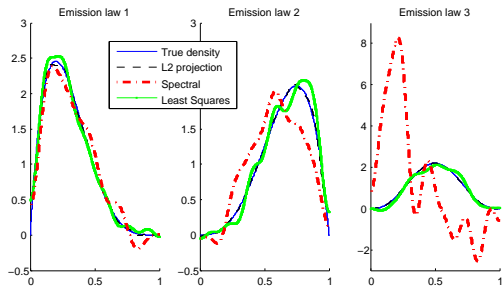
Identifiability/inference theoretical results in nonparametric HMMs

- 1 Identifiability in non parametric finite translation HMMs and extensions
- 2 Identifiability in non parametric general HMMs
- 3 Generic methods
- 4 Inverse problem inequalities
- 5 Further works**

Sensitivity to the linear dependence assumption

(L. Lehéricy, mémoire de M2, 2015).





Likelihood methods

Back to Kruskal : identifiability holds when Q is full rank and F_1, \dots, F_K are distinct probability distributions, but on the basis of the $(2K + 1)[(K^2 - 2K + 2) + 1]$ -th marginal distribution.
(Alexandrovitch et al., 2016)

→ Full likelihood methods

(Oracle inequalities, L. Lehéricy, on going work)

Others

- **Bayesian methods** E. Vernet : consistency of the posterior distribution (EJS 2015); rates of concentration for the posterior distribution (Bernoulli, in revision).
- **Clustering/Estimation of the filtering and marginal smoothing distributions** (Y. De Castro, EG, S. Le Corff, IEEE IT, to appear)
- **Estimation of K** (L. Lehéricy, 2016, submitted)
- **Adaptive estimation of each emission density** using Lepski's method (L. Lehéricy, on going work)
- **Seasonal HMMs and climate applications** (A. Touron, work in progress)

Thank you for your attention !