Specification of Interlevel Relations for Agent Models in Multiple Abstraction Dimensions

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Abstract. Multiagent systems for a certain application area can be modelled at multiple levels of abstraction. Interlevel relations are a means to relate models from different abstraction levels. Three dimensions of abstraction often occurring are the process abstraction, temporal abstraction, and agent cluster abstraction dimension. In this paper a unifying formalisation is presented that can be used as a framework to specify interlevel relations for any of such dimensions. The approach is illustrated by showing how a variety of different types of abstraction relations between multi-agent system models can be formally specified in a unified manner.

Keywords: interlevel relation, abstraction dimension

1 Introduction

Different models describing the same process in reality, usually are based on different conceptualisations of this process. As they are models of the same process in which different concepts used may refer to the same aspects or elements in reality, a natural question is how in general two of such descriptions can be related to each other. In the literature on reduction relations it is described, for example, how by an interlevel relation a functional or cognitive model (or theory) can be related to a biochemical or neurological model, (e.g., [5], [20]). In [29] this notion was further developed by formalising (context-dependent) interlevel relations between cognitive agent models and neurological agent models. More in general, abstraction levels between multiagent system models may concern different dimensions of abstraction. For example, process abstraction can be considered from neurological to cognitive models (as addressed by the literature on reduction relations), and from cognitive to behavioural models (as is done in information hiding or from a behaviourist perspective; e.g., [4]). As another example, in *temporal abstraction* the detailed steps of a process are left out of consideration and instead the patterns are considered emerging from such steps. Yet another example is agent cluster abstraction: abstracting from individual agents to consider populations, groups or clusters of agents instead, as often happens in organisational modelling, ecological modelling, and system dynamics.

In [8] a three-dimensional abstraction framework was introduced, addressing how a multi-agent model can be positioned in the three-dimensional space defined by the dimensions mentioned. Relations between models at different abstraction levels were not addressed in [8]. The focus of the current paper is to provide a unified specification format for such interlevel relations. The unified formalisation for interlevel relations introduced here will cover (at least) these abstraction dimensions. The unifying formalisation was inspired by the use of interpretation mappings from logic (e.g., [28]) to describe reduction relations between cognitive and neurological agent models in [22] and [29], and to describe a mapping from a single agent model to a multi-agent model in [11].

The formalisation of interlevel relations introduced here subsumes a number of notions known from the literature. As a first example, for the process abstraction dimension it subsumes not only reduction relations between cognitive and neurological models (e.g., [5], [20], [22], [29]), but also relations between behavioural agent models and cognitive agent models (e.g., [4], [27], [28], [29]). Furthermore, for the temporal abstraction dimension it subsumes the relation between emerging properties of a multi-agent system and the basic mechanisms for the agents (e.g., [1], [2], [3], [6]). Moreover, for the agent cluster dimension it subsumes the relation between the relation between agent-based models and population-based models (e.g., [7], [15], [30], [31]) or organisation models (e.g., [11], [14], [18], [23], [26], [32]).

The introduced unifying formalisation can play a useful role as a specification format to handle different abstraction levels in analysis and design of multi-agent systems. By making explicit the relationships as part of the specifications, model descriptions (or *views*) at different levels of abstraction can be freely used while in the meantime keeping track on how they relate. This supports working at an appropriate level of abstraction for different subprocesses (e.g., with stakeholders in a more abstract fashion).

The paper is organised as follows. In Section 2 the unified notion of interlevel relation is introduced in a general form. Section 3 addresses how the notion applies to specification of process abstraction interlevel relations, Section 4 of temporal abstraction interlevel relations, and Section 5 of agent cluster abstraction interlevel relations. Finally, Section 7 is a discussion.

2 Specification of Interlevel Relations: Format

Multi-agent system models are usually specified by temporal relationships (dynamic properties) between states; e.g., [3], [6], [10], but also [1], [15], [19], [25]. Interlevel relations between two models relate the states and dynamic properties specified as part of one model, to states and properties specified as part of the model at the other abstraction level. The introduced general format for specification of interlevel relations between two models involves three key elements:

- (1) An *ontology mapping* to relate basic state properties of the higher level model to state properties of the lower level.
- (2) A dynamic property mapping extending the basic ontology mapping to dynamic properties in a (reified) temporal predicate logical language (cf. [16]). This mapping can be applied to dynamic properties that are part of the higher level model, or to dynamic properties that describe patterns in the behaviour of the higher level model.
- (3) Logical entailment relations for dynamic properties. Such relationships formally expressed as valid logical implications between temporal predicate logical expressions indicate how mapped higher level properties can be related to properties of the lower level model.

These three key elements are explained in more detail below; see also the overall view depicted in Fig. 1. The format was inspired by the use of interpretation mappings from logic to describe reduction relations between cognitive and

neurological models in [22]. Within logic (e.g., [28]) an interpretation mapping φ^* from one theory T_2 to another one T_1 usually is defined as a (1) a mapping φ^* from formulae F in the language of T_2 to formulae in the language of T_1 , fulfilling (2) compositionality, and (3) $T_2 \vdash F \Rightarrow T_1 \vdash \varphi^*(F)$ for any formula F. The three key elements follow these criteria.

Basic Ontology Mapping An ontology mapping can be used to map a basic concept (atom) in the ontology used for the higher level to a concept in the ontology of the lower level (criterion (1) of an interpretation mapping). For example, suppose at some level basic state property b₂ is given. Moreover, suppose at a lower level state property b_1 is given. Then by a *basic ontology mapping* ϕ property b_2 can be mapped onto b_1 , i.e., $\varphi(b_2) = b_1$. When also b_1 is a basic concept in the ontology of its level, then this φ is just a mapping between basic concepts. Note that sometimes also general relations, for example between numbers or time points, are involved that do not belong to any particular level; they are assumed to be mapped onto themselves: $\varphi(T1 < T2) = T1 < T2$. It is also possible to define an ontology mapping by mapping basic concepts of one ontology to more complex expressions in the other ontology. For example, suppose b₁ is the complex property $\exists V [b_1(V) \& V \ge 0.3]$ where $b_1(V)$ is a basic concept at the lower level. Then an interlevel relation can be defined as: $\varphi(b_2) = \exists V, [b_1(V) \& V \ge 0.3]$. A basic ontology mapping φ can be extended to more complex state properties in a compositional manner, based on rules as: $\phi(A \& B) = \phi(A) \& \phi(B), \phi(A \lor B) = \phi(A) \lor$ $\phi(B), \phi(A \Rightarrow B) = \phi(A) \Rightarrow \phi(B), and \phi(\neg A) = \neg \phi(A).$

Dynamic Property Mapping For dynamic properties a sorted temporal predicate logic format is assumed with traces and state properties as first class citizens (e.g., [9], [16]). Basic atoms are represented as follows:

at(γ , T1, a) in trace γ at time T1 state property a is true

at(γ , T2, \neg b) in trace γ at time T2 state property b is not true

When only one fixed trace γ is assumed, the notation can also be simplified to at(T1, a); however, then trace comparison properties (cf. [8], [9]) cannot be expressed. *Dynamic properties* are (sorted) predicate logical expressions built on such atoms, where the state properties a are expressed as terms (reification; cf. [16]). To map dynamic properties a *compositionality principle* is used. For example, a dynamic property such as the temporal relation from observation to (temporary) belief, can be mapped by compositionality on the temporal relation from sensor state to sensory representation, when an ontology mapping from state properties observation, resp. belief to sensor state resp. sensory representation is assumed. In general an interlevel relation is defined by a mapping φ^* extending the ontology mapping φ as follows:

$$\begin{array}{lll} \boldsymbol{\phi}^{\star}(A \& B) &= \phi^{\star}(A) \& \phi^{\star}(B) & \boldsymbol{\phi}^{\star}(A \lor B) &= \phi^{\star}(A) \lor \phi^{\star}(B) & \boldsymbol{\phi}^{\star}(A \Rightarrow B) &= \phi^{\star}(A) \Rightarrow \phi^{\star}(B) \\ \boldsymbol{\phi}^{\star}(\neg A) &= \neg \phi^{\star}(A) & \boldsymbol{\phi}^{\star}(\forall \top A) &= \forall \top \phi^{\star}(A) & \boldsymbol{\phi}^{\star}(\exists \top A) &= \exists \top \phi^{\star}(A) \end{array}$$

In addition, for basic constituents $at(\gamma, T, a)$ of dynamic properties ϕ^* is defined as

 $\boldsymbol{\phi}^{*}(\operatorname{at}(\gamma, \mathsf{T}, a)) = \operatorname{at}(\boldsymbol{\phi}^{*}(\gamma), \mathsf{T}, \boldsymbol{\phi}(a))$

where $\phi^*(\gamma)$ is just a name for the mapped trace. Thus a mapping ϕ^* is obtained crossing the line between higher level and lower level in Fig. 1. For example, using the composition rules, the property

 $\forall T1, T2 \; [\; [\; T1 < T2 \; \; \& \; \; at(\gamma, \; T1, \; a) \; \; \& \; \; at(\gamma, \; T2, \; b) \;] \; \Rightarrow \; \exists T3 \; at(\gamma, \; T3, \; c) \; \;]$

is mapped by φ^* as follows

Logical Relationships between Properties Usually a mapped higher level model is not exactly equal to a given lower level model, but instead (according to criterion (3) of an interpretation mapping) it can be logically related to it by a *logical entailment relation* between dynamic properties. As an example, suppose an ontology mapping is given with $\varphi(a_2) = a_1$ and $\varphi(d_2) = d_1$ and as part of the higher level model a relationship $a_2 \Rightarrow d_2$ is specified. Moreover, suppose in the lower level model relationships $a_1 \Rightarrow b_1$, $b_1 \Rightarrow c_1$, $c_1 \Rightarrow d_1$ are specified as part of the model. By compositionality $a_2 \Rightarrow d_2$ is mapped to the lower level dynamic property $a_1 \Rightarrow d_1$, i.e.,

 $\mathbf{\phi}^{*}(\mathbf{a}_{2} \Longrightarrow \mathbf{d}_{2}) = \mathbf{\phi}^{*}(\mathbf{a}_{2}) \Longrightarrow \mathbf{\phi}^{*}(\mathbf{d}_{2}) = \mathbf{a}_{1} \Longrightarrow \mathbf{d}_{1}$

The latter lower level dynamic property is not part of the lower level model itself, but can be logically related to such dynamic properties by a valid logical implication:

 $[a_1 \mathop{\Rightarrow} b_1 \And b_1 \mathop{\Rightarrow} c_1 \And c_1 \mathop{\Rightarrow} d_1] \ \Rightarrow \ a_1 \mathop{\Rightarrow} d_1$

So the interlevel relation is specified between the dynamic property $a_2 \Rightarrow d_2$ and the three dynamic properties $a_1 \Rightarrow b_1$, $b_1 \Rightarrow c_1$, $c_1 \Rightarrow d_1$ by a combination of compositionality and a logical relationship expressed as a valid logical implication.



Fig. 1. Overall format of an interlevel relation specification

Such a logical implication for multiple properties can be graphically represented in a hierarchical manner as depicted in Fig. 1 under the line between higher and lower level. In the subsequent three sections it will be shown how the general notion of interlevel relation briefly introduced here can be applied for the three different types of abstraction dimensions considered: the process abstraction (extended ontology mapping π^*), temporal abstraction (θ^*), and agent cluster abstraction (ρ^*) dimension.

3 Process Abstraction Dimension

For the process abstraction dimension, agent processes can be conceptualised from an external behavioural perspective (e.g., [4], [27]) or from an internal cognitive or neurological perspective (e.g., [8], [22], [29]). In this section interlevel relations are discussed between for a given example process. In [8] an instant Internet dating context was used as a toy example to illustrate different abstraction levels. In this example at the behavioural level a person P (with respect to the Internet dating service agent ID) is described as an agent by three behavioural properties BP1 to BP3, respectively, for generating a date request to ID (based on observed dopamine lack), proposing an activity (when a candidate is offered by ID), and performing the date (when ID communicates that the candidate agrees). To keep the example a bit simple the detailed matchmaking aspects to pair date requests by ID (based on the persons' profiles) have been left out of consideration. For this example the ontology used at the behavioural level makes use of atoms such as observes(P, a), communication(P1, a, P2), and performs(P, b), where a is a world state property and b is an action, and P, P1, P2 are agents (i.e., persons or the agent ID). The behavioural properties BP1, BP2, BP3 describe a person P's process to come to a date. Here act(X) denotes an activity that fits adrenalin level X (i.e., the higher X, the more active the activity).

BP1 Requesting for a date

- If P observes that his or her dopamine lack is high,
- then *P* will request for a date
 - \forall T, P [[at(γ , T, observes(P, body(dopaminelack, high)))
 - $\Rightarrow \exists T1 [T1 \ge T \& at(\gamma, T1, communication(P, date_request, ID))]$

BP2 Proposing an activity

- If it was communicated to *P* that *Q* agrees in a date,
- and P observes that his or her adrenaline level is X
- then P will propose to perform activity act(X).
 - $\begin{array}{l} \forall \mathsf{T},\mathsf{P},\mathsf{X} \; [\; [\; \mathsf{at}(\gamma,\mathsf{T},\mathsf{communication}(\mathsf{ID},\;\mathsf{agrees}(\mathsf{Q}),\mathsf{P})) \; \& \; \mathsf{at}(\gamma,\mathsf{T},\;\mathsf{observes}(\mathsf{P},\;\mathsf{body}(\mathsf{adrenaline},\;\mathsf{X})\;)) \; \& \\ \Rightarrow \; \exists \mathsf{T1} \; [\; \mathsf{T1} \geq \mathsf{T} \;\& \; \mathsf{at}(\gamma,\;\mathsf{T1},\;\mathsf{communication}(\mathsf{P},\;\mathsf{wants}(\mathsf{P},\;\mathsf{act}(\mathsf{X})),\;\mathsf{ID})) \;] \end{array}$

BP3 Performing an agreed activity

- If it was communicated to *P* that *Q* agrees in having a date
- and *P* observes adrenaline level *X*
- and it was communicated to P that Q wants to do activity act(X),
- then P will perform act(X) with Q.
- \forall T, P, X [[at(γ , T, communication(ID, agrees(Q), P)) & at(γ , T, observes(P, body(adrenaline, X))) & at(γ , T, communication(ID, wants(Q, act(X)), P))
 - ⇒ \exists T1 [T1 ≥ T & at(γ, T1, performs(P, date(act(X), Q)))]

At the *cognitive level* the ontology used is based on atoms sensing(P, a), belief(P, a), desire(P, b), intention(P, b), effector(P, b), where sensing refers to the same state as observes and effector to the same state as performs. The ontology mapping π of basic behavioural state properties onto cognitive state properties is defined by

 π (observes(P, a)) = sensing(P. a) π (performs(P, b)) = effector(P. b)

The extension π^* of this mapping to dynamic properties is defined by *compositionality*. What remains is how a mapped behavioural dynamic property relates to (multiple) dynamic properties from the cognitive model. A mapped behavioural dynamic property may be considered as a kind of shortcut. For the

Internet dating example at the cognitive level a number of dynamic properties relate relevant beliefs, desires and intentions. For example, the following simplified properties describe the cognitive process to generate a date request.

LCP1 Generating a desire to date

If *P* senses that her or his dopamine lack is high

then *P* will have the desire to obtain a date

 $\forall T, P \text{ at}(\gamma, T, \text{sensing}(P, \text{body}(\text{dopaminelack}, \text{high}))) \Rightarrow \exists T1 \geq T \text{ at}(\gamma, T1, \text{desire}(P, \text{date}))$

LCP2 Generating an intention to request a date based on a desire

If *P* has the desire to obtain a date,

then *P* will have the intention to request a date.

 $\forall T, P \text{ at}(\gamma, T, \text{desire}(P, \text{date}) \Rightarrow \exists T1 \geq T \text{ at}(\gamma, T1, \text{intention}(P, \text{date}_{request}))$

LCP3 Requesting for a date based on the intention

If *P* has an intention to request a date,

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then P will request ID for a date
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\forall T, P \text{ at}(\gamma, T, \text{intention}(P, \text{date\_request}) \Rightarrow \exists T1 \geq T \text{ at}(\gamma, T1, \text{ communication}(P, \text{date\_request}, ID))
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The other cognitive properties LCP4 to LCP10 are similar. For this case the following entailment relations specified as valid implications can be used to define the interlevel relation.

More examples of interlevel relations for this process abstraction dimension, in particular, for the relation between cognitive and neurological level models can be found in [22] and [28].

4 Temporal Dimension

Temporally local descriptions specify the steps made by the basic mechanisms of a process, whereas temporally more global descriptions describe patterns that result or emerge from these basic mechanisms. Such temporally global properties are often used to express (behavioural) requirements on a model, and can be used in formal verification (e.g., [9], [12], [14]). Temporal interlevel relations can be viewed as a description of to which temporally local descriptions such emerging patterns relate, as also is addressed in compositional verification and model checking; see for example, [2], [6], [9], [12], [17], [26]. Patterns emerging over time can be of many different types, for example varying from the last drop that makes the bucket flow over, to monotonicity relations within one trace or between different traces, and equilibria.

Temporal interlevel relations can be defined within any process abstraction level from neurological to cognitive or behavioural. Also in the temporal dimension, at different levels different ontologies may be used. Therefore in general temporal interlevel relations are specified by (1) using an ontology mapping θ from the temporally higher level ontology to the temporally lower level ontology, (2) compositionally extending θ to θ^* for more complex expressions, and (3) logically relating a mapped property to a number of properties from the lower level model. As in Section 3, temporal interlevel relations will be illustrated for the dating case study. An example of a temporal interlevel relation at the behavioural process abstraction level will be discussed, in particular, concerning a body state that is achieved.

GBP1 Body state achieved with low dopamine lack

If at some point in time T the dopamine lack is high then at a later time point T1 the dopamine lack will be low. $\forall T, P, V \ [at(\gamma, T, body(P, dopaminelack, high)) \Rightarrow$ $\exists T1, V1 \ [T1 \ge T \& at(\gamma, T1, body(P, dopaminelack, low)]$

Note that this property is formulated in terms of an ontology for the temporally global

level (which is taken qualitative). The ontology mapping $\boldsymbol{\theta}$ maps the temporally global atoms on atoms (taken quantitative) at the local level as follows:

 $\begin{array}{l} \pmb{\theta}(at(\gamma, \mathsf{T}, \mathsf{body}(\mathsf{P}, \mathsf{dopaminelack}, \mathsf{high})) = \exists \mathsf{V} \; at(\gamma, \mathsf{T1}, \mathsf{body_state}(\mathsf{P}, \mathsf{dopaminelack}, \mathsf{V}) \;) \; \& \; \mathsf{V}{\geq}0.5 \\ \pmb{\theta}(at(\gamma, \mathsf{T}, \mathsf{body}(\mathsf{P}, \mathsf{dopaminelack}, \mathsf{low})) \; = \exists \mathsf{V} \; at(\gamma, \mathsf{T1}, \mathsf{body_state}(\mathsf{P}, \mathsf{dopaminelack}, \mathsf{V}) \;) \; \& \; \mathsf{V}{<}0.5 \end{array}$

Dynamic property GBP1 relates to behavioural dynamic properties BP1, BP2, BP3; BBP1, BPP2 at the temporally local level describing an interaction between the behavioural processes of the person and the dynamics of the body state. The first three were described already in Section 3; the last two are as follows:

BBP1 Generating a body state observation

If in *P* body state property *B* has strength V < 0.5

then it will be observed by *P* that *B* is low.

 \forall T, P, V [[at(γ , T, body_state(P, B, V)) & V<0.5] \Rightarrow

- $\exists T1 \ [T1 \ge T \& at(\gamma, T1, observes(P, body(B, low)))$
- If in *P* body state property *B* occurs of strength $V \ge 0.5$
- then it will be observed by *P* that *B* is high.
- \forall T, P, V [[at(γ , T, body_state(P, B, V)) & V \ge 0.5] \Rightarrow \exists T1 [T1 \ge T & at(γ , T1, observes(P, body(B, high)))

BBP2 From a date to its effect

If T a date with Q doing an activity of type X is performed

and the level of the body state for adrenaline qualifies as *X*

- then at a later time point Tl within time duration D after T the body states for adrenaline and dopamine lack will have levels <0.5.
- $\forall \mathsf{T},\,\mathsf{P},\,\mathsf{Q},\,\mathsf{X},\,\mathsf{V}\,[~[~at(\gamma,\,\mathsf{T},\,\mathsf{performs}(\mathsf{P},\,\mathsf{date}(\mathsf{act}(\mathsf{X}),\,\mathsf{Q})))~\&~$
 - at(γ , T, body_state(P, adrenaline, V)) & has_qualification(V, X)]
 - ⇒ ∃T1, W1, W2 [T1≥T & T1 ≤ T+ D & at(γ, T1, body_state(P, adrenaline, W1)) & W1<0.5 & at(γ, T1, body_state(P, dopaminelack, W2)) & W2<0.5]

These behavioural properties together entail the global property GBP1:

BBP1: Body Observation & BP2: Requesting Date &

BP3: Proposing Activity & BP4: Performing Date &

BBP2: Body Modification $\Rightarrow \theta^*(GBP1: Low Body State Achieved)$

Thus a temporal interlevel relation is obtained.

5 Agent Cluster Dimension

In the third dimension considered a population, group or cluster of agents can be abstracted to one agent. For example, in the extreme case the whole population of individuals can be considered as one super-agent. An example of such a perspective is the Gaia hypothesis which considers the earth as a whole as one intelligent organism (cf. [21]). As another example, in [11] it was addressed how an ant society which uses pheromones on the ground as a form of shared extended mind can be interpreted as a single agent by using a mapping from a single agent model onto the multi-agent model of the ant society. Other literature which relates a single agent perspective to multiple agents can be found in [23] where the mind is considered to emerge as an interaction of a large number of agents within the brain, and in [7], [14], [18], [32].

Models at different levels of the agent cluster dimension describe a process in reality according to different grain-sizes of the basic entities modelled as agents. Each of the agents used in a higher level model refers to an element in reality that is modelled as a group or cluster of agents in a lower level model. Given this, in an agent cluster interlevel relation, to relate two models at different agent cluster levels, each agent in the higher level model is related to a cluster of agents in the lower level model. Moreover, states and properties of a higher level agent are related to states and properties of individual agents in the set (cluster) of lower level agents that relates to this higher level agent. In this section by a few examples it will be discussed how an agent cluster interlevel relation can be defined for behavioural models and for cognitive models. First a basic ontology mapping ρ is defined. Properties from the higher cluster level are collective properties that often refer to an aggregated number for the size or strength of a certain cluster or property thereof. The extended ontology mapping ρ^* maps a cluster property DP onto the aggregated property $\rho^*(DP)$ (which is the lower level property 1 in Fig. 1), and this aggregated property is implied by a conjunction of the individual properties IP(P) for the different individuals P1, ..., P5 (which correspond to lower level model property 1 to 4 in Fig. 1). To define within the lower level an aggregated property two issues need to be addressed:

- (i) a language element is needed to represent *accumulation* over a group of agents
- (ii) the clusters and the agents belonging to them may be *dynamic*; in the lower level ontology no state properties may be available to indicate explicitly which agents belong to which cluster at some point in time

For issue (i), this can be solved in a sorted temporal predicate logical language by introducing the following abbreviation for summation of values V1 or V2, depending on the truth of a formula φ containg a free variable X over a sort S: $\Sigma_{X:S}$ case(ψ , V1, V2) = V. Here for any (temporal) formula ψ , the expression case(ψ , V1, V2) indicates the value V1 if ψ is true, and V2 otherwise. In particular, when V1 = 1 and V2 = 0 is chosen, this represents the number of elements X within sort S for which ψ is true. This construct can be considered logically as a short notation for a large disjunction of conjunctions over many instances. It will be applied to define the basic ontology mapping from the higher to the lower cluster level, with S the sort of all agents and P in ψ the variable X. For this instantiation of S the following naming will be used:

agg_number_of_agents_with(V, ψ) = $\Sigma_{P:S}$ case(ψ , 1, 0) = V

Due to issue (ii), usually it is not possible to simply relate state properties of the higher level to state properties at the lower level. However, it is still possible to map the temporal atoms of the form $at(\gamma, T, a)$ with a higher level state property a onto *dynamic* properties at the lower level. For the Internet dating case, as an illustration the following (dynamic) clusters are considered:

- persons in the process of obtaining a date: those who requested a date but did not yet start to perform a date (R)
- persons performing a date (D)
- persons not in a process of dating: not in a date nor in a process of obtaining a date (N); this is the rest of the population

Behavioural Cluster Interlevel Relations To apply the solutions of issues (1) and (2) at the behavioural level, as a first example, consider the state property has_size(D, V). Whether at some point in time T an agent belongs to this group D can be expressed in a formula ψ_D as a dynamic property as follows.

 $\psi_D(\gamma, T, P) \equiv \exists A, Q \ at(\gamma, T, performs(P, date(A, Q))))$

So, this is a case for which the membership of the cluster can be characterised by a lower level state property: performs(P, date(A, Q)).

Note that this formula contains trace γ , agent P and time point T as a free variable. This formula ψ_D is used to define the ontology mapping $\boldsymbol{\rho}$ as follows:

 $p(at(\gamma, T, has_size(D, V)))) = agg_number_of_agents_with(V, \psi_D)$

For the sake of simplicity here the names of the traces γ at the higher and lower level are taken identical.

Next, consider the state property has_size(R, V). For this group R all individuals are taken into account who did communicate a request for a date until the current point in time, but did not yet start a date. Whether at some point in time T an agent belongs to group R is expressed as a dynamic property ψ_R at the lower cluster level as follows (note there is no state property available this time).

 $\begin{array}{l} \psi_{\mathsf{R}}(\mathsf{P},\mathsf{T}) \equiv \exists \mathsf{T1} ~ [~ \mathsf{T1} \leq \mathsf{T} ~ \& ~ \mathsf{at}(\gamma,\mathsf{T1},\mathsf{communication}(\mathsf{P},\mathsf{date_request},\mathsf{ID}))) \\ \& ~ \neg \exists \mathsf{T2}, ~ \mathsf{A}, ~ \mathsf{Q} ~ [~ \mathsf{T1} \leq \mathsf{T2} \leq \mathsf{T} ~ \& ~ \mathsf{at}(\gamma,\mathsf{T2},\mathsf{performs}(\mathsf{P},\mathsf{date}(\mathsf{A},\mathsf{Q}))))]] \end{array}$

This formula ψ_{R} can be used to define:

 $\rho(at(\gamma, T, has_size(R, V))) = agg_number_of_agents_with(V, \psi_R)$

Finally, for the agents related to cluster N it can be expressed that they are all agents not in R nor in D: $\psi_N = \neg \psi_R \& \neg \psi_D$.

 $\rho(at(\gamma, T, has_size(N, V))) = agg_number_of_agents_with(V, \psi_N)$

This ontology mapping ρ can be extended by compositionality to a mapping ρ^* for dynamic properties. As an example, the following dynamic property LCBP1 is taken; here N(do) denotes the subgroup of N with high dopamin lack.

LCBP1 Dynamics of group N

- If N has size V,
- and the part N(do) of N with dopamine lack level high has size V1, and D has size V2,
- then at some later point in time N will have size $V + (\alpha V2 \beta V1) \Delta t$
- at(y, T, has_size(N, V)) & at(y, T, has_size(N(do), V1)) & at(y, T, has_size(D, V2))
- $\Rightarrow \exists T1 \ [T1 \ge T \& at(\gamma, T1, has_size(N, V + (\alpha V2 \beta V1) \Delta t))]$

Here α is the fraction per time unit in D finishing a date, and β is the fraction per time unit in N requesting a date. Taking $\psi_{N(do)}(\gamma, T, P) = \psi_N \& at(\gamma, T, body(P, dopaminelack,$ high)), it holds:

- $\boldsymbol{\rho}^*(\text{LCBP1}) = \boldsymbol{\rho}^*(\text{at}(\gamma, \mathsf{T}, \text{has}_{\text{size}}(\mathsf{N}, \mathsf{V})) \& \text{at}(\gamma, \mathsf{T}, \text{has}_{\text{size}}(\mathsf{N}(\text{do}), \mathsf{V1})) \& \text{at}(\gamma, \mathsf{T}, \text{has}_{\text{size}}(\mathsf{D}, \mathsf{V2}))$ $\Rightarrow \exists T1 [T1 \ge T \& at(\gamma, T1, has_size(N, V + (\alpha V2 - \beta V1) \Delta t))])$
- **ρ***(at(γ, T, has_size(N, V))) & **ρ***(at(γ, T, has_size(N(do), V1))) & **ρ***(at(γ, T, has_size(D, V2))) $\Rightarrow \exists T1 [T1 \ge T \& \rho^*(at(\gamma, T1, has_size(N, V + (\alpha V2 - \beta V1) \Delta t))))$
- agg_number_of_agents_with(V, ψ_N) & agg_number_of_agents_with(V1, $\psi_{N(do)})$ & agg_number_of_agents_with(V2, yD) ⇒ ∃T1 [T1≥T & agg_number_of_agents_with(V + (αV2 - βV1) Δt , ¬ ψ_R & ¬ ψ_D)

This property can be related by a (hybrid) logical entailment relation to the individual behavioural properties for the agents involved, for example, using an assumption on uniform distribution over time of the individual time points that dopamin lack becomes high. If this is a uniform fraction β of N per time unit, then within Δt there are $\beta N\Delta t$ among them that start to have high dopamin lack. From the individual behavioural property BP1 for each of these agents it follows that within Δt they will generate a date request after Δt ; thus $\beta V1\Delta t$ date requests are generated, which makes these agents not part of N anymore, but of R. Similarly, assuming that dates have a fixed duration, it can be established that from group D a uniform fraction α will be make a transition to N. Thus the third part of the interlevel relation for LCBP1 can be specified as

 $\forall P [BP1(P) \& BP2(P) \& BP3(P)] \Rightarrow p^*(LCBP1)$

This completes the interlevel relation specification for LCBP1.

Cognitive Cluster Interlevel Relations Also at the cognitive process abstraction level cluster interlevel relations can be established. As an example, the temporally local dynamic property LCCP1 connecting a collective desire to a collective intention.

LCCP1 From collective desire to collective intention to request a date

- If the part *N*(*desire*(*date*)) of *N* with desire to request a date has size *V*, and the part *N*(*intention*(*date_request*)) of *N* with intention to ask for a date has size V1,
- then the part N(intention(date_request)) of N with intention to ask for a date will have size $V+(VI (VI - V)/d) \Delta t$ at(y, T, has_size(N(desire(date), V)) & at(y, T, has_size(N(intention(date_request), V1)) ⇒ \exists T1 [T1≥T & at(γ , T1, has_size(N(intention(date_request), V+(V1 (V1-V)/d) \Delta t))

Roughly spoken this expresses that within cluster N, a collective desire for a date within N affects the strength of a collective intention according to the formula V+(V1 (V1- V)/d) ∆t. To map this higher level dynamic property onto an aggregation of lower level properties, first the ontology mapping ρ for the collective temporal atoms at(γ , T, has_size(N(C), V) with C a cognitive concept is addressed (in this case C applies to a desire and an intention). In a manner similar to the approach above this mapping can be defined by

 $\rho(at(\gamma, T, has_size(N(C), V))) = agg_number_of_agents_with(V, \psi_{N,C(P)})$

with $\psi_{N,C(P)} = \neg \psi_R \& \neg \psi_D \& at(\gamma, T, C(P))$. Here for C = intention(X), the term C(P) denotes intention(P, X), and for C = desire(X), the term C(P) denotes desire(P, X). Next the mapping is extended to dynamic property LCCP1:

 $\begin{array}{l} \pmb{\rho}^{*}(at(\gamma, \mathsf{T}, has_size(\mathsf{N}(desire(date)), \mathsf{V1})) \& at(\gamma, \mathsf{T}, has_size(\mathsf{N}(intention(date_request)), \mathsf{V})) \\ \Rightarrow \exists \mathsf{T1} \ [\mathsf{T1} \geq \mathsf{T} \& at(\gamma, \mathsf{T1}, has_size(\mathsf{N}(intention(date_request)), \mathsf{V+}(\mathsf{V1} \ (\mathsf{V1-V})/d) \ \Delta t))) \end{array}$

= $\rho^*(at(\gamma, T, has_size(N(desire(date)), V1))) \& \rho^*(at(\gamma, T, has_size(N(intention(date_request)), V))) \& V1>V \Rightarrow \exists T1 [T1\geq T \& \rho^*(at(\gamma, T1, has_size(N(intention(date_request)), V+(V1 (V1-V)/d) \Delta t))))$

= agg_number_of_agents_with(V1, ψ_{N,desire(P, date)}) & agg_number_of_agents_with(V, ψ_{N,intention(P, date_request)}) & V1>V ⇒ ∃T1 [T1≥T & agg_number_of_agents_with(V+(V1 (V1-V)/d) Δt))), ψ_{N,intention(P, date_request)})

This aggregated lower level property, onto which the collective property was mapped, expresses how within cluster N, the aggregated number of agents with a desire for a date affects the aggregated number of agents with the related intention. Indeed, in a manner similar to the behavioural case, such a property can be logically related to the temporally local dynamic property LCP2 at the cognitive process abstraction level that relates an individual desire to an individual intention, applied to the set of agents having this desire. Therefore the third part of the interlevel relation for LCCP1 can be specified as

 $\forall \mathsf{P} \ \mathsf{LCP2}(\mathsf{P}) \implies \mathbf{\rho}^*(\mathsf{LCCP1})$

This completes the interlevel relation specification for LCCP1.

Neurological Cluster Interlevel Relations An interlevel relation at the neurological (or physiological) process abstraction level can be addressed according to an approach similar to the aggregation approach for the cognitive level. However, a difference is that here the individual states themselves have certain gradations or levels of activation, which can be used as a kind of weights in the aggregation process. The following form of aggregation for the activation levels of X can be used:

 $agg_strength_of(V1, \,at(\gamma, \, T, \,activation(X, \, V)) \) \equiv \ V1 = \Sigma_{P:S} \, case(at(\gamma, \, T, \,activation(X, \, V)), \, V, \, 0)$

This takes as aggregated strength the sum of all activation values over all agents. The aggregated strength defined in this manner can be used in the mapping of the strength of the collective variant of the same neural state. Given this form of aggregation of activation levels, further the approach as for the cognitive level can be followed.

6 Discussion

The specification format for interlevel relations (e.g., [5]) introduced was inspired by the concept of interpretation mapping from logic to describe relations between logical theories (e.g., [28]), which has played a quite powerful role in mathematical logic and the logical foundations of mathematics. This concept has also been used to describe reduction relations between cognitive and neurological agent models (e.g., [20], [22], [29]). The work reported in the current paper generalises and applies this idea to a much wider spectrum of abstraction dimensions (taken from [8]). As a basis for the formalisation in a hybrid specification format reified sorted temporal predicate logic was used (e.g., [16]), but alternative choices may work equally well, for example, nonreified temporal predicate logic (using time arguments within each predicate), or any other temporal logic which is able to handle numbers. Moreover, the underlying conceptual and logical framework may well be related and combined with further work in ontology and database schema specification; e.g., [13].

Such interlevel relation specifications provide a useful conceptual and formal tool in analysis and design of multi-agent processes. For example, in the analysis of oneto-many negotiation processes (such as in [11]) it may be conceptually useful to be able to switch perspective between the 'many' role as many individual agents or as one super-agent (thus obtaining a conceptualisation as one-to-one negotiation), and to specify the relationship between the two conceptualisations. In the same analysis it may be useful to specify temporally global properties as a form of requirements (required emerging properties; for example, termination of the negotiation process) vs temporally local properties for mechanisms to realise these requirements (for example, the agents' decision rules). A temporal interlevel relation specification can be used to indicate which of the specified temporally local properties (are assumed to) realise which required temporally global properties. Many similar cases can be found in analysis and design of organisation models. In such cases, having models available at different abstraction levels, and knowing their relationships can provide a good basis to manage the complexity of the analysis and design process, both at an individual analyst/designer level, and in communication between different persons involved. At a more abstract level the main ideas can become and stay more transparent to everyone involved (including less technical stakeholders). One particular use is when a top down approach is followed in which first temporally global behavioural requirements are formulated for units consisting of larger groups of agents, and during the process these are (gradually) refined to temporally local properties for individual agents involving their internal cognitive and/or neurological dynamics (e.g., [12]). These show some possibilities for the perspective to use the presented hybrid (logical/numerical) formal specification framework to establish relationships between different multi-agent system models, for example, between behavioural, cognitive and neurological agent models (e.g., [4], [20], [22], [27], [29]), between emerging dynamic properties and mechanisms underlying them (e.g., [1], [2], [3], [6], [9], [10], [12], [15], [17], [19], [25], [26]), between population-based and individual agent-based models (e.g., [7], [21], [24], [30], [31]), and between organisation models and agent models (e.g., [14], [18], [23], [32]).

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